

L #	Hits	Search Text	DBs	Time Stamp
1	L1 152685	((load\$3 unload\$3 park\$3 unpark\$3 retract\$3 ship\$4 withdraw\$3 css (contact adj start adj stop)) near5 (head\$1 transducer\$1 slider\$1 arm\$1 hga hsa stack assembly (load adj beam\$1) (e adj block))).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 16:33
2	L2 56206	((actuator motor coil positioner vcm) near5 (current\$1 drive\$3 power accelerat\$4) near5 (zero\$3 null\$6 stop\$4 no none ceas\$5 off coast\$3)).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 16:35
3	L3 52809	((actuator motor coil positioner vcm) near5 (zero\$3 null\$6 stop\$4 no none ceas\$5 off coast\$3) near5 (current\$1 drive\$3 power accelerat\$4)).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 16:36
4	L4 59115	(2 3).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 16:36
5	L6 4097	(bemf (back adj (emf electromotive (electro adj motive))).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 16:41
6	L8 282468	((speed\$1 rate\$1 velocit\$3) near5 (constant\$2 predetermin\$6 fixed)).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 16:54
7	L10 433134	((speed\$1 rate\$1 velocit\$3) near5 (regulat\$4 control\$4)).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 16:57
8	L11 264809	((speed\$1 rate\$1 velocit\$3) near5 (set sets setting setable govern\$3 hold holds holding held maintain\$3)).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:10
9	L12 709997	(8 10 11).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:11
10	L13 193	(1 and 4 and 6 and 12).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:14
11	L14 0	(1 and 4 and 6 and 12).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:12
12	L15 2	(1 and 4 and 6).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:13
13	L16 11	(1 and 4 and 12).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:13
14	L17 4	(1 and 6 and 12).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:13
15	L18 10	(4 and 6 and 12).bi.	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:13

L #	Hits	Search Text	DBs	Time Stamp
16	L19 27	15 16 17 18	EPO; JPO; IBM TDB	2002/08/19 17:14
17	L20 220	13 19	USPAT; EPO; JPO; IBM TDB	2002/08/19 17:15